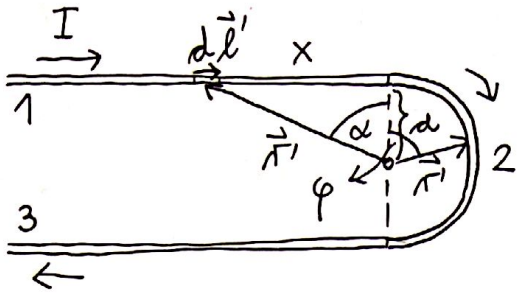


1. KOLOKVIJ

1 VODNIK V OBLIKI ČRKE "U"



$$\vec{B}(\vec{r}) = \frac{\mu_0}{4\pi} \int \frac{\vec{j}(\vec{r}') \times (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} d^3\vec{r}'$$

$$\vec{j}(\vec{r}') d^3\vec{r}' = I d\vec{l}'$$

$\vec{r} = \vartheta$ (izhodišče = središče)

$$\vec{B} = \frac{\mu_0 I}{4\pi} \int \frac{\vec{r}' \times d\vec{l}'}{r'^3}$$

- segment 1

$$\vec{r}' = \begin{bmatrix} x \\ a \\ \vartheta \end{bmatrix}, \quad d\vec{l}' = \begin{bmatrix} dx \\ \vartheta \\ \vartheta \end{bmatrix} \Rightarrow \vec{r}' \times d\vec{l}' = \begin{bmatrix} \vartheta \\ \vartheta \\ -a dx \end{bmatrix}$$

$$r' = \sqrt{x^2 + a^2}$$

$$B_1 = -\frac{\mu_0 I a}{4\pi} \int_{-\infty}^0 \frac{dx}{(x^2 + a^2)^{\frac{3}{2}}}$$

$$x = a \tan \alpha \Rightarrow dx = \frac{a}{\cos^2 \alpha} d\alpha, \quad x^2 + a^2 = a^2 (1 + \tan^2 \alpha) = \frac{a^2}{\cos^2 \alpha}$$

$$\int_{-\infty}^{\vartheta} \frac{dx}{(x^2 + a^2)^{\frac{3}{2}}} = \frac{a}{a^3} \int_{-\frac{\pi}{2}}^{\vartheta} \frac{d\alpha}{\cos^2 \alpha} \cos^3 \alpha = \frac{1}{a^2} \sin \alpha \Big|_{-\frac{\pi}{2}}^{\vartheta} = \frac{1}{a^2}$$

$$B_1 = -\frac{\mu_0 I}{4\pi a} \left(-\frac{1}{2} \cdot \frac{\mu_0 I}{2\pi a} \right)$$

→ rezultat lahko dobimo tudi kot POLOVICO rezultata za rami vodnik, saj gre za simetrijsko točko

+ { - segment 3 : $B_3 = B_1 = -\frac{\mu_0 I}{4\pi a}$

- segment 2

$$\vec{r}' \times d\vec{l}' = -\hat{e}_2 a \cdot a d\varphi = -a^2 d\varphi \hat{e}_2, \quad r' = a$$

$$B_2 = -\frac{\mu_0 I}{4\pi} \int_{\vartheta}^{\pi} \frac{a^2 d\varphi}{a^3} = -\frac{\mu_0 I}{4\pi a} \pi$$

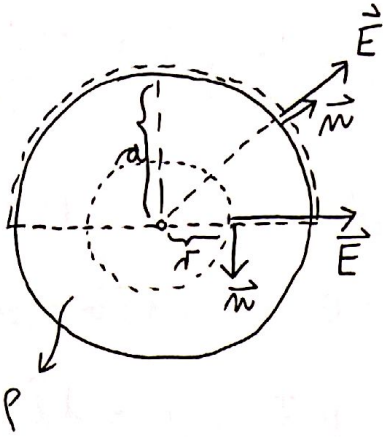
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+ { - skupaj : $B = B_1 + B_2 + B_3 = -\frac{\mu_0 I}{4\pi a} (\pi + 2)$

karže
NAUZDOL!

↳ predznak

2 SILA NA POLOVICO NABITEGA VALVA



$$\left. \begin{aligned} \epsilon_0 \cdot E \cdot \underbrace{2\pi r l}_S &= \rho \cdot \underbrace{\pi r^2 l}_V \\ E &= \frac{\rho r}{2\epsilon_0} \end{aligned} \right\} +$$

→ Gauss na valji s polmerom r , ZNOTRAJ, $r \leq a$!

- svobod valja

$$\vec{F}_e = \epsilon_0 \oint \left[\vec{E} (\vec{E} \cdot \vec{n}) - \frac{1}{2} E^2 \vec{n} \right] dS$$

$\frac{1}{4} +$

$$\left. \begin{aligned} \vec{E} \parallel \vec{n} &\Rightarrow \vec{E} (\vec{E} \cdot \vec{n}) = E \vec{n} E = E^2 \vec{n} \\ \vec{F}_{e1} &= \frac{\epsilon_0}{2} \int E^2 \vec{n} dS \\ E &= \frac{\rho r}{2\epsilon_0}, \quad \vec{n} = \begin{bmatrix} \cos\varphi \\ \sin\varphi \end{bmatrix}, \quad dS = r d\varphi \cdot l \\ \vec{F}_{e1} &= \frac{\epsilon_0}{2} \frac{\rho^2 r^2}{4\epsilon_0^2} r l \int_0^{2\pi} \begin{bmatrix} \cos\varphi \\ \sin\varphi \end{bmatrix} d\varphi = \frac{\rho^2 r^3 l}{4\epsilon_0} \hat{e}_y \end{aligned} \right\}$$

- preseki valja (ploskev skozi središče)

$\frac{1}{4} +$

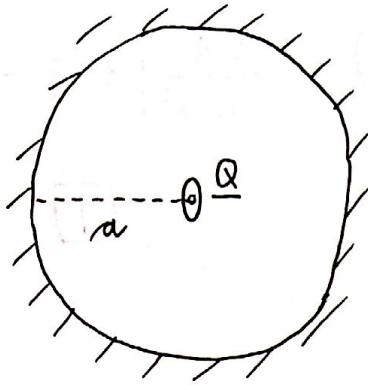
$$\left. \begin{aligned} \vec{E} \perp \vec{n} &\Rightarrow \vec{E} \cdot \vec{n} = 0 \\ \vec{F}_{e2} &= -\frac{\epsilon_0}{2} \int E^2 \vec{n} dS \\ E &= \frac{\rho r}{2\epsilon_0}, \quad \vec{n} = -\hat{e}_y, \quad dS = l dr \\ \vec{F}_{e2} &= \frac{\epsilon_0}{2} \frac{\rho^2 l}{4\epsilon_0^2} \hat{e}_y \int_{-a}^a r^2 dr = \frac{\rho^2 l}{8\epsilon_0} 2 \frac{a^3}{3} \hat{e}_y = \frac{\rho^2 a^3 l}{12\epsilon_0} \hat{e}_y \end{aligned} \right\}$$

- skupaj

$$+ \left\{ \vec{F}_e = \vec{F}_{e1} + \vec{F}_{e2} = \frac{\rho^2 a^3 l}{3\epsilon_0} \hat{e}_y, \quad \boxed{\frac{\vec{F}_e}{l} = \frac{\rho^2 a^3}{3\epsilon_0} \hat{e}_y} \right.$$

kaže NAVZGOR na zgornjo polovico!

3 TOČKASTI KVADRUPOL V OKROGLI VOTLINI PREVODNIKA



$$\underline{Q} = Q \begin{bmatrix} -\frac{1}{2} & & \\ & -\frac{1}{2} & \\ & & 1 \end{bmatrix}$$

$$V_Q(\vec{r}) = \frac{1}{4\pi\epsilon_0} \cdot \frac{1}{2} \sum_{ij} \frac{Q_{ij} r_i r_j}{r^5}$$

$$\frac{1}{4} \left\{ \begin{aligned} V_Q(\vec{r}) &= \frac{1}{4\pi\epsilon_0} \cdot \frac{1}{2} Q \frac{1}{r^5} \left(\underbrace{-\frac{1}{2}x^2 - \frac{1}{2}y^2}_{-\frac{1}{2}r^2 \sin^2\vartheta} + \underbrace{r^2}_{r^2 \cos^2\vartheta} \right) = \frac{Q}{16\pi\epsilon_0 r^3} \underbrace{(2\cos^2\vartheta - \sin^2\vartheta)}_{3\cos^2\vartheta - 1} \\ V_Q(\vec{r}) &= \frac{Q}{8\pi\epsilon_0 r^3} \cdot \frac{3\cos^2\vartheta - 1}{2} = \frac{Q}{8\pi\epsilon_0 r^3} P_2(\cos\vartheta) \end{aligned} \right.$$

- rešitev v votlini

$$V(r, \vartheta) = \sum_l [A_l r^l + B_l r^{-(l+1)}] P_l(\cos\vartheta)$$

$$\frac{1}{4} \left\{ \begin{aligned} \text{1. RP: } V(r \rightarrow 0, \vartheta) = V_Q(r, \vartheta) &\Rightarrow \text{imamo } l = \underline{2} \\ B_2 &= \frac{Q}{8\pi\epsilon_0} \end{aligned} \right.$$

$$V(r, \vartheta) = \left[A_2 r^2 + \frac{Q}{8\pi\epsilon_0 r^3} \right] P_2(\cos\vartheta)$$

$$+ \left\{ \begin{aligned} \text{2. RP: } V(r = a, \vartheta) = 0 &\Rightarrow A_2 = -\frac{Q}{8\pi\epsilon_0 a^5} \end{aligned} \right.$$

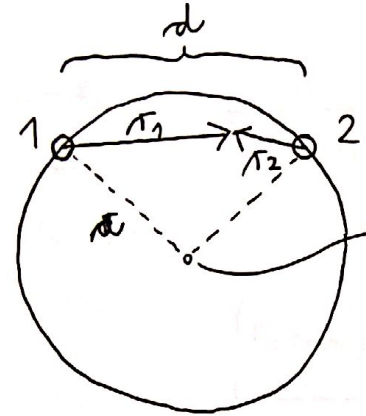
$$V(r, \vartheta) = \frac{Q}{8\pi\epsilon_0} \left(\frac{1}{r^3} - \frac{r^2}{a^5} \right) P_2(\cos\vartheta)$$

- inducirani naboji na površini

$$+ \left\{ \sigma_{IND} = -\epsilon_0 \left(-\frac{\partial V}{\partial r} \right)_{r=a} = \frac{Q}{8\pi\epsilon_0} \left(-\frac{3}{a^4} - \frac{2a}{a^5} \right) P_2(\cos\vartheta) = \frac{5Q}{8\pi\epsilon_0 a^4} P_2(\cos\vartheta) \right.$$

$$\begin{aligned}
 \frac{1}{4} \left\{ \begin{aligned}
 q_{IND} &= \int \sigma_{IND} dS = - \frac{5Q}{8\pi\epsilon_0 a^4} \int_{\cos\vartheta = -1}^1 P_2(\cos\vartheta) 2\pi a^2 d(\cos\vartheta) = \\
 &= - \frac{5Q}{4\epsilon_0 a^2} \int_{\cos\vartheta = -1}^1 \frac{1}{2} (3\cos^2\vartheta - 1) d(\cos\vartheta) = - \frac{5Q}{8\epsilon_0 a^2} \left[3 \cdot \frac{2}{3} - 2 \right] = 0 \\
 \boxed{q_{IND} = 0} & \qquad \qquad \qquad \boxed{1}
 \end{aligned} \right.
 \end{aligned}$$

4 UPOR PREVODNE PLOŠČICE,



navit valj:

$$\begin{aligned}
 e &= 2\pi\epsilon_0 E l r \\
 E &= \frac{e}{2\pi\epsilon_0 l r} = \frac{\lambda}{2\pi\epsilon_0 r} = - \frac{\partial V}{\partial r}
 \end{aligned}$$

$$+ \left\{ \begin{aligned}
 U_1 &= - \frac{\lambda}{2\pi\epsilon_0} \ln \frac{r_1}{a} \\
 U_2 &= \frac{\lambda}{2\pi\epsilon_0} \ln \frac{r_2}{a}
 \end{aligned} \right.$$

$$U(r_1, r_2) = U_1 + U_2 = \frac{\lambda}{2\pi\epsilon_0} \ln \frac{r_2}{r_1}$$

$$\frac{1}{4} + \left\{ \begin{aligned}
 \text{elektroda 1: } U(\delta, d-\delta) &= \frac{\lambda}{2\pi\epsilon_0} \ln \frac{d-\delta}{\delta} \approx \frac{\lambda}{2\pi\epsilon_0} \ln \frac{d}{\delta} \\
 \text{elektroda 2: } U(d-\delta, \delta) &= \frac{\lambda}{2\pi\epsilon_0} \ln \frac{\delta}{d-\delta} \approx - \frac{\lambda}{2\pi\epsilon_0} \ln \frac{d}{\delta} \\
 \text{razlika: } U_0 &= + \frac{\lambda}{2\pi\epsilon_0} 2 \ln \frac{d}{\delta} \quad (\text{tako teče od 1 do 2})
 \end{aligned} \right.$$

$$\frac{1}{4} \left\{ \begin{aligned}
 \text{ob elektrode 1: } E_\delta &= \frac{\lambda}{2\pi\epsilon_0 \delta} = \frac{U_0}{2\delta \ln \frac{d}{\delta}} \\
 I = \sigma E_\delta \cdot \pi \delta D &= \frac{\pi \sigma U_0 D}{2 \ln \frac{d}{\delta}} \Rightarrow \boxed{R = \frac{2 \ln \frac{d}{\delta}}{\pi \sigma D}}
 \end{aligned} \right.$$

$\frac{1}{4}$ Analogija s primerom dveh valjev je možna, ker so ekvipotencialne ploskve krožnice, prav tako pa so ležavnice tudi silnice, tako da je na robu ploščice robni pogoj izpolnjen! 1