

2. KOLOKVIJ

1 +
$$\begin{cases} I = I_0 \sin \omega t, & e = \int I dt = -\frac{I_0}{\omega} (\cos \omega t - 1) = \frac{I_0}{\omega} (1 - \cos \omega t) \\ E = \frac{e}{\epsilon_0 S} = \frac{I_0}{\epsilon_0 S \omega} (1 - \cos \omega t) \end{cases}$$

+
$$\begin{cases} \vec{\nabla} \times \vec{B} = \epsilon_0 \mu_0 \frac{\partial \vec{E}}{\partial t}, & B \cdot 2\pi r = \epsilon_0 \mu_0 \pi r^2 \dot{E} = \epsilon_0 \mu_0 \pi r^2 \frac{I_0}{\epsilon_0 S} \sin \omega t \\ B = \frac{\mu_0 I_0}{2S} r \sin \omega t \end{cases}$$

$$P = \frac{1}{\mu_0} EB = \frac{I_0^2}{2\epsilon_0 S^2 \omega} r \sin \omega t (1 - \cos \omega t)$$

+
$$\begin{cases} \int P dS = P(r=a) 2\pi a da = \frac{I_0^2 da}{\epsilon_0 S^2 \omega} \pi a^2 \sin \omega t (1 - \cos \omega t) = \\ = \frac{I_0^2 da}{\epsilon_0 S \omega} \sin \omega t (1 - \cos \omega t) \end{cases}$$

+
$$\begin{cases} W_e = \frac{1}{2} \epsilon_0 E^2 \cdot S da = \frac{I_0^2 da}{2\epsilon_0 S \omega^2} (1 - \cos \omega t)^2 \\ \dot{W}_e = \frac{I_0^2 da}{2\epsilon_0 S \omega^2} 2(1 - \cos \omega t)(+\omega \sin \omega t) = \frac{I_0^2 da}{\epsilon_0 S \omega} \sin \omega t (1 - \cos \omega t) \end{cases}$$

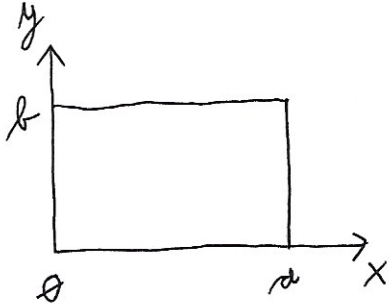
$\frac{1}{4}$
$$\begin{cases} w_m = \frac{B^2}{2\mu_0} = \frac{\mu_0 I_0^2}{8S^2} r^2 \sin^2 \omega t \\ W_m = \int w_m dV = \int w_m 2\pi r dr \cdot dr = \frac{\mu_0 I_0^2}{8S^2} da 2\pi \sin^2 \omega t \int_0^a r^3 dr = \\ = \frac{\mu_0 I_0^2 da}{16\pi S^2} \underbrace{\pi^2 a^4}_{S^2} \sin^2 \omega t = \frac{\mu_0 I_0^2 da}{16\pi} \sin^2 \omega t \end{cases}$$

+
$$\frac{W_{m0}}{W_{e0}} = \frac{\mu_0 I_0^2 da}{16\pi} \cdot \frac{2\epsilon_0 S \omega^2}{I_0^2 da} = \frac{\mu_0 \epsilon_0 S \omega^2}{8\pi} = \frac{S}{8\pi} \left(\frac{\omega}{c_0}\right)^2 = \frac{S}{8\pi} \left(\frac{2\pi}{\lambda}\right)^2$$

+
$$\frac{W_{m0}}{W_{e0}} = \frac{\pi S}{2 \lambda^2}$$
 kvazistatični približek: majhen $\omega \Rightarrow \lambda \gg \sqrt{S} \Rightarrow \frac{W_{m0}}{W_{e0}} \ll 1 \checkmark$

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- valovna enačba

$$\left[\nabla_{\perp}^2 + \underbrace{\left(\frac{\omega^2}{\epsilon_0^2} - k^2 \right)}_{\alpha^2} \right] H_z = 0$$

$$\nabla_{\perp}^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}, \quad H_z(x,y) = X(x)Y(y)$$

$$\rightarrow X''Y + XY'' + \alpha^2 XY = 0$$

$$\frac{X''}{X} + \frac{Y''}{Y} + \alpha^2 = 0, \quad \underbrace{\frac{X''}{X}}_{-\alpha_x^2} = - \underbrace{\frac{Y''}{Y}}_{-\alpha_y^2} - \alpha^2$$

$$+ \begin{cases} X'' + \alpha_x^2 X = 0 \Rightarrow X = A_x \cos \alpha_x x + B_x \sin \alpha_x x \\ Y'' + \alpha_y^2 Y = 0 \Rightarrow Y = A_y \cos \alpha_y y + B_y \sin \alpha_y y \end{cases}$$

- robni pogoji za TE: $H_{\perp}|_a = 0 \Rightarrow \frac{\partial H_z}{\partial n}|_a = 0$

$$+ \begin{cases} x=0, a: \frac{\partial H_z}{\partial x} = X'Y = 0 \text{ za } \forall y \Rightarrow X' = 0 \\ X'(0) = 0 \Rightarrow B_x = 0 \\ X'(a) = 0 \Rightarrow \alpha_x a = m\pi, \quad \alpha_x = \frac{m\pi}{a} \\ y=0, b: \frac{\partial H_z}{\partial y} = XY' = 0 \text{ za } \forall x \Rightarrow Y' = 0 \\ Y'(0) = 0 \Rightarrow B_y = 0 \\ Y'(b) = 0 \Rightarrow \alpha_y b = n\pi, \quad \alpha_y = \frac{n\pi}{b} \end{cases}$$

$$\left(\frac{m\pi}{a} \right)^2 + \left(\frac{n\pi}{b} \right)^2 = \frac{\omega^2}{\epsilon_0^2} - k^2 \Rightarrow \omega_{mn} = \epsilon_0 \sqrt{k^2 + \left(\frac{m\pi}{a} \right)^2 + \left(\frac{n\pi}{b} \right)^2}$$

$m=0,1,2,\dots$
 $n=0,1,2,\dots$
NE sta 0!

- pasovna širina

$$+ \begin{cases} \omega_1 = \omega_{10} (k=0) = \epsilon_0 \frac{\pi}{a} = \frac{2}{3} \frac{\pi \epsilon_0}{b} \\ \omega_2 = \omega_{01} (k=0) = \epsilon_0 \frac{\pi}{b} \end{cases} \Delta\omega = \omega_2 - \omega_1 = \frac{1}{3} \frac{\pi \epsilon_0}{b}$$

plazma: $\epsilon_0 \rightarrow \epsilon = \frac{\epsilon_0}{\sqrt{1 - \frac{\omega_p^2}{\omega^2}}} \Rightarrow \left(\frac{m\pi}{a} \right)^2 + \left(\frac{n\pi}{b} \right)^2 = \frac{\omega^2}{\epsilon_0^2} \left(1 - \frac{\omega_p^2}{\omega^2} \right) - k^2$

$$+ \omega_{mn} = \epsilon_0 \sqrt{k^2 + \left(\frac{\pi}{a} \right)^2 + \left(\frac{m\pi}{a} \right)^2 + \left(\frac{n\pi}{b} \right)^2}$$

$$\frac{\omega^2}{\epsilon_0^2} - \frac{\omega_p^2}{\epsilon_0^2} = \frac{\omega^2}{\epsilon_0^2} - \left(\frac{\pi}{a} \right)^2$$

$$\frac{1}{4} \begin{cases} \omega_1' = \omega_{10} (k=0) = \epsilon_0 \sqrt{2 \frac{\pi^2}{a^2}} = \sqrt{2} \frac{\pi \epsilon_0}{a} = \frac{2\sqrt{2}}{3} \frac{\pi \epsilon_0}{b} \\ \omega_2' = \omega_{01} (k=0) = \epsilon_0 \sqrt{\frac{\pi^2}{a^2} + \frac{\pi^2}{b^2}} = \frac{\pi \epsilon_0}{b} \sqrt{\frac{4}{9} + 1} = \frac{\sqrt{13}}{3} \frac{\pi \epsilon_0}{b} \\ \Delta\omega' = \omega_2' - \omega_1' = \frac{\sqrt{13} - 2\sqrt{2}}{3} \frac{\pi \epsilon_0}{b} \Rightarrow \frac{\Delta\omega'}{\Delta\omega} = \sqrt{13} - 2\sqrt{2} = 0.78 \end{cases}$$

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3) ena prečka: $p_e = l e$, $\dot{p}_e = l \dot{e} = l I$, $\ddot{p}_e = l \ddot{e}$

+ { - krizna antena: $I_1 = I_0 \cos \omega t$, $\ddot{p}_{e1} = l I_1 \hat{e}_x = -l I_0 \omega \sin \omega t \hat{e}_x$
 $I_2 = I_0 \sin \omega t$, $\ddot{p}_{e2} = l I_2 \hat{e}_y = l I_0 \omega \cos \omega t \hat{e}_y$

$$\vec{B} = -\frac{\mu_0}{4\pi r_0 r} \hat{e}_r \times \ddot{p}_e(t_r) \quad \ddot{p}_e = l I_0 \omega (\hat{e}_y \cos \omega t - \hat{e}_x \sin \omega t)$$

+ {
$$\vec{B} = -\frac{\mu_0 l I_0 \omega}{4\pi r_0 r} (\hat{e}_r \times \hat{e}_y \cos \omega t_r - \hat{e}_r \times \hat{e}_x \sin \omega t_r)$$

$$\hat{e}_r = \begin{bmatrix} \cos \varphi \sin \vartheta \\ \sin \varphi \sin \vartheta \\ \cos \vartheta \end{bmatrix}, \quad \hat{e}_r \times \hat{e}_x = \begin{bmatrix} \vartheta \\ \cos \vartheta \\ -\sin \varphi \sin \vartheta \end{bmatrix}, \quad \hat{e}_r \times \hat{e}_y = \begin{bmatrix} -\cos \vartheta \\ \vartheta \\ \cos \varphi \sin \vartheta \end{bmatrix}$$

$$\vec{B} = -\frac{\mu_0 l I_0 \omega}{4\pi r_0 r} \begin{bmatrix} -\cos \vartheta \cos \omega t_r \\ -\cos \vartheta \sin \omega t_r \\ \sin \vartheta (\cos \varphi \cos \omega t_r + \sin \varphi \sin \omega t_r) \end{bmatrix}$$

$\cos(\omega t_r - \varphi)$

+ {
$$\vec{P} = \frac{1}{\mu_0} \vec{E} \times \vec{B} = \frac{1}{\mu_0} (-\hat{e}_r \times \epsilon_0 \vec{B}) \times \vec{B} = -\frac{\epsilon_0}{\mu_0} [\underbrace{\vec{B}(\hat{e}_r \cdot \vec{B})}_{\vartheta} - \hat{e}_r B^2] = \frac{\epsilon_0}{\mu_0} \hat{e}_r B^2$$

\downarrow
 $P \propto B^2$

+ {
$$B^2 = B_r^2 [\cos^2 \vartheta \cos^2 \omega t_r + \cos^2 \vartheta \sin^2 \omega t_r + \sin^2 \vartheta \cos^2(\omega t_r - \varphi)]$$

$$\langle B^2 \rangle = B_r^2 \left(\frac{1}{2} \cos^2 \vartheta + \frac{1}{2} \cos^2 \vartheta + \frac{1}{2} \sin^2 \vartheta \right) = B_r^2 \frac{1}{2} (1 + \cos^2 \vartheta)$$

+ {
$$\langle \int \vec{P} d\vec{S} \rangle \propto B_r^2 r^2 \int \frac{1}{2} (1 + \cos^2 \vartheta) 2\pi d(\cos \vartheta) = B_r^2 r^2 2\pi \frac{1}{2} (2 + \frac{2}{3}) = B_r^2 r^2 2\pi \cdot \frac{4}{3}$$

- ena sama sama antena

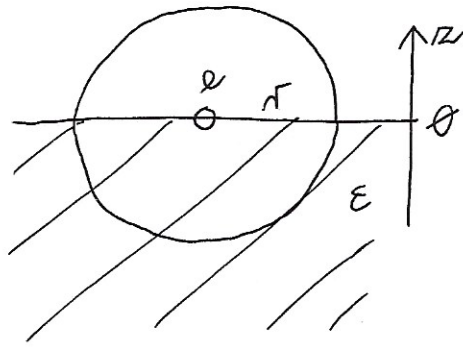
$\frac{1}{4}$ {
$$\ddot{p}_e = 2l I_0 \omega \cos \omega t \hat{e}_z, \quad \vec{B} = 2B_r \hat{e}_r \times \hat{e}_z \cos \omega t$$

$$\hat{e}_r \times \hat{e}_z = \begin{bmatrix} \sin \varphi \sin \vartheta \\ -\cos \varphi \sin \vartheta \\ \vartheta \end{bmatrix}, \quad B^2 = 4B_r^2 \sin^2 \vartheta \cos^2 \omega t, \quad \langle B^2 \rangle = 2B_r^2 \sin^2 \vartheta$$

+ {
$$\langle \int \vec{P} d\vec{S} \rangle \propto 2B_r^2 r^2 \int \sin^2 \vartheta 2\pi d(\cos \vartheta) = B_r^2 r^2 2\pi \cdot \frac{8}{3} \Rightarrow \text{KRIŽNA sva 2-krat MANJ}$$

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$\frac{1}{4}$ $\left\{ \begin{array}{l} \nabla^2 U = 0 \quad \text{razen v nabojih} \\ \downarrow \\ U(r) \propto \frac{1}{r} P_0(\cos\vartheta) = \frac{1}{r} \quad (l=0) \end{array} \right.$
 zaradi robnih pogojev
 v $r=R$ in $r \rightarrow \infty$

$+$ $\left\{ U(r) = \begin{cases} -\frac{e_1}{4\pi\epsilon_0 r} & , r > R \\ -\frac{e_2}{4\pi\epsilon_0 r} & , r < R \end{cases} \right.$
 predfaktorja (konstanti)
 postavimo kar na $\frac{e_{1,2}}{4\pi\epsilon_0}$
 \hookrightarrow ju IŠČEMO!

$\frac{1}{4}$ $\left\{ \begin{array}{l} \text{robni pogoj na meji: } (E_1)_\parallel = (E_2)_\parallel \text{ ali } V_1 = V_2 \\ \hookrightarrow e_1 = e_2 \end{array} \right.$

$\frac{1}{4}$ $\left\{ \begin{array}{l} \text{povezava z originalnim nabojem} \rightarrow \text{Gaussov izrek:} \\ e = \int \vec{D} \cdot d\vec{S} = \frac{e_1}{4\pi\epsilon_0 r^2} \epsilon_0 r^2 2\pi + \frac{e_2}{4\pi\epsilon_0 r^2} \epsilon_0 \epsilon r^2 2\pi = \\ = \frac{1}{2} e_1 + \frac{\epsilon}{2} e_2 = \frac{1+\epsilon}{2} e_1 \end{array} \right.$

$+$ $\left\{ \begin{array}{l} e_1 = \frac{e}{\frac{\epsilon+1}{2}} = e_2 \Rightarrow \boxed{U(r) = -\frac{e}{4\pi\epsilon_0 \frac{\epsilon+1}{2} r^2}} \quad \text{POVSOD!} \end{array} \right.$ ✓

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